

DUCO Collaboration of Welding Robot

Selection Manual for Welding Scenarios

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Product Introduction

DUCO Collaborative Welding Robot is equipped with two core functions: graphical interaction and lead-teaching. It comes standard with a welding process package, enabling users to quickly perform various welding tasks such as spot welding, corner welding, traverse welding, repetitive welding, overlay welding, and multi-pass welding. Additionally, the optional external axis plug-in package allows for the expansion of additional welding application scenarios and customization of various forms of welding workstations.

This robot offers outstanding repeatability and trajectory accuracy. It is compatible with laser vision weld seam tracking systems, allowing for flexible deployment as well as automatic tracking and correction functionalities. As a result, it can achieve long-term, uninterrupted output of high-quality and stable weld seams. This capability contributes to cost reduction and increased efficiency in automated welding production across industries including automotive parts manufacturing, shipbuilding, engineering machinery production, new energy sectors (e.g., solar or wind power), aerospace applications, and metal processing.

Product Features

🗋 Intuitive User Interface

- Graphical user interface, high user acceptance.
- Drag-and-drop programming, fast learning for beginners.

High Performance Product

- High precision ensures high-quality weld output.
- High-precision visual integration for diverse functions.

Fully Functional

- Trajectory teaching streamlines welding interaction.
- Rich button interface enables more possibilities.

💥 Rich Communication Interfaces.

- Rich communication interface, compatible with major brands.
- Compatible with welding machine brands, for plug-and-play use.

Welding Process Package

- Professional welding package balances expertise and usability.
- Supports spot, corner, oscillation, reciprocating, and multi-layer welding.

|⟨=→) Extensive Functionality Expansion

- External axis and multi-machine cooperation expand welding applications.
- Complete development interfaces facilitate building diverse welding workstations.





		2		
		GCR10-1300-W	GCR5-910-W	GCR3-618-W
Max Paylo	pad	10kg	5kg	3kg
Degress of	f Freedom	6	6	6
Max TCP S	Speed	3.8m/s	3.6m/s	1.0m/s
Max Straig	ght-line Speed	1.5m/s	1.5m/s	0.8m/s
Reach		1300mm	917mm	618mm
Repeatab	bility	±0.03mm	±0.02mm	±0.02mm
Joint	Range		Max Speed	
J6	±360°	225°/s	225°/s	225°/s
J5	±360°	225°/s	225°/s	225°/s
J4	±360°	225°/s	225°/s	225°/s
J3	±360°	225°/s	225°/s	225°/s
J2	±360°	180°/s	225°/s	225°/s
J1	±360°	180°/s	225°/s	225°/s
Tool Inter	face	GB/T 14468.1-50-4-M6(eqv ISO 9409-1)		
End Joint	I/O	2 Dig I/O, 24V,0.6A	2 Dig I/O, 24V,0.6A	2 Dig I/O, 24V,0.6A
Power Sup	pply	100-240VAC 47-63Hz 10A		
Power Co	onsumption	Typical Power Consumption400W	Typical Power Consumption200W	Typical Power Consumption200W
Installation		Installed in any Direction		
IP Class		IP65	IP65	IP65
Ambient Temperature Range		-10°C-50°C	-10°C-50°C	-10°C-50°C
Storage Temperature Range		-40°C-55°C	-40°C-55°C	-40°C-55°C
Robot Dir	mensions	1512x388x205mm	1100x330x200mm	769x315x150mm
Robot Pa	ckage Size	958x508x516mm	698x588x450mm	532x431x330mm
Net/Gross Weight		37.8kg/46kg	22kg/30kg	13kg/20kg

Base Flange

Control Box

The controller is used to control the robot's operations such as loading and unloading, grasping, polishing, handling, welding, gluing and oiling, as well as realizing the input and output control. The latest DUCO controller has tiny volume while taking into account the safety and flexibility, and has better performance in the field of human cooperation. It can be fully compatible with multiple series of robots, and also can be independently applied to automatic control systems.



User Interface

16 Channels(8 channels can be equipped with functional DI)
PNP,L:-3V-5V,H:11V-30VDC,2-15mA
TON:50ms TOFF:50ms

DO

User DO	16 Channels(8 channels can be equipped with functional DO)
VOUT	PNP, 22-28V,Max:0.5A
LOUT	PNP, <2A(When exceeding 2A, the user needs to expand the power supply)
Switching Time	TON:50ms TOFF:50ms

A I/O

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input voitage Signai	U-TUV ACCULACY TT%

Analog Voltage Input 2	Input Impedance	48ΚΩ	
	Resolution	12-bit	
Analog Voltage Output 2	Output Voltage Signal 0-10V Accuracy ±1%		
	Resolution	12-bit	

SDI

Emergency Signal Input	1Channels(Passive signal, dry contact input)
Protective Stop Input	1Channels(Passive signal, dry contact input)
Configurable Secure Input	2Channels(Passive signal, dry contact input)

SDO

Configurable Secure Outp	ut 2Channels(PNP Active Signal)		
Emergency Stop Feedback OutpliChannels(PNP Active Signal)			
VOUT	23.52V-25.2VDC (Max 0.5A ScP)		

通讯/COM

CAN	1Channels,bps configurable 10k、20k、50k、100k、125k、250k、500k、1000k bps	
RS485	1Channels,bps configurable 4800、9600、19200、38400、115200 bps	
LAN	2-way (1-way gigabit, 1-way 100Mbit) Support MODBUS TCP, PROFINFT, TCP IP	
EtherCAT	1Channels,EtherCAT COM	
INC A+, A-; B+, B-;Z+,Z-	Working voltage: 24VDC Frequency: <200KHz Input: square wave signal	

• Base Flange







GCR10-1300-W

GCR5-910-W

GCR3-618-W

• Tool Flange



GCR10-1300-W



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GCR5-910-W/GCR3-618-W

300

400

900

600 700 800

450

350

10Kg

-9Kg -8Kg

-7Kg -6Kg

Lz (mm)

5.0Kg

— 4.0Kg — 3.0Kg

— 2.5Kg

Lz (mm)

— 3.0Kg — 2.5Kg

-2.0Kg

Lz (mm)

1000 1100

500

400

Payload Diagram

GCR10-1300-W Payload Diagram



Lxy (mm)

250

200

150

100 50

0

125

0

100 200 300 400 500

GCR5-910-W Payload Diagram

GCR3-618-W Payload Diagram





Welding Process Package

DUCO proprietary welding process package integrates welding machine configuration, welding settings, process parameter settings, vision sensor settings, as well as starting, ending, arc tracking, weaving, and multi-layer multi-pass welding functions, and various quick commands, eliminating complicated interface operations. It is convenient to operate and adjust, and a regular worker can operate it within a short time, providing customers with a safer and more efficient solution.



Welding Setup



Spot Welding

1981	TE project_1	RM IM IM MM tcp1 Okg default	JOG 100% 空间JOG 100%	Finder Att LS C 5600
DUCO CONST Partian XIN	<	weld/arc.jspf*	已打开租床	1016 (XX (R#E#
Q #38	1	主程序	NO	支量 医数 运行
⊕ # 动	2	Start ····	#2	HARANARCAR ~
<の 程序	4	undefined	H做方向	□Y □Z
а 1911			基素电流 电流高度比利系数K	4
8 8			最大补偿距离限制	
() () ()			Z/5/#j(mm)	100
X				
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External Shaft Process Package

Supporting the extension of robot degrees of freedom through an external axis or the transformation of the workpiece position through an external axis, which can be controlled separately or in conjunction with the robot, provides more possibilities for welding scene applications.

The following are the supported external axis models:

Brand	Drive Model	Communication Protocol
HUICHUAN SV630N/SV660N		EtherCAT



External Axis Setup

External Axis Calibration